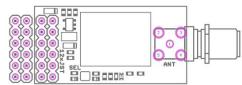


Features: Reference: ELT0165

- Continuous navigation in urban environment, even at signal loss with speed or wheel-tick information from the vehicle
- Intended for fleet management or micromobility applications
- On-board low noise 3.3 V voltage regulator and RF filter for noise blocking
- USB, I2C (SDA, SCL), SPI and UART (Tx, Rx), RAW sensor data out
- SMA active antenna connector
- 12 pin 6x 2 row holes with pitch 2.54 mm
- Time pulse LED
- · Wheeltick input
- · u-center GPS evaluation software
- Extensive visualization and evaluation features
- Battery holder for 3 V type 621 Lithium battery
- Dimensions: 36x19 mm
- Weight 6.8 gram





RXD/SPI MOSI®@+5V
TXD/SPI MISO@@SCL/SPI SLK
DIR(@@SDA/SPI CS_N
USB DP(@)USB DM
WHEELTICK(@@TIME PULSE
SAFEBOOT_N@@GND

GNSS FEATURES	
Receiver type	92-channel u-blox M9 engine GPS L1 C/A, QZSS L1 C/A/S, GLONASS L10F, Beidou B1I, Galileo E1B/C, SBAS L1 C/A: WAAS, EGNOS, MSAS, GAGAN
GNSS platform	Concurrent GNSS
Oscillators	TCXO

PERFORMANCE			
Position accuracy	1.5 m CEP	(with SBAS)	
(GPS+GLO+GAL+BDS)			
Attitude accuracy (GPS)		(with SBAS)	
Position error during	3D Gyro + 3	3D Accel + Wheel Ticks	2%
GNSS loss	3D Gyro + :	3D Accel	10%
Max nav. update rate	50 Hz		
Nav update rate (PVT)	5 Hz		
Navigation latency	15 ms		
Max sensor output rate	100 Hz		
Acquisition	Cold start	Hot start	Aided start
GPS+GLO+GAL+BDS	24 s	2 s	3 s
GPS+GLO	25 s	2 s	2 s
BDS+GLO	28 s	2 s	3 s
Velocity accuracy	0.08 m/s		
Dynamic attitude	Heading	0.3 deg	
accuracy	Pitch	0.4 deg	
	Roll	0.6 deg	
Sensitivity:		<u> </u>	
Tracking and Navigation	-159 dBm		
Reacquisition	-158 dBm		

-147 dBm

-159 dBm

Cold start Hot start



OTHER FEATURES	
Anti-jamming	Additional SAW filter and LNA, jamming detection and reporting
Anti-spoofing	Spoofing detection and reporting
Memory	Flash
Operating	0 °C to +50 °C
temperature	
Supply voltage	4.5 V to 5.5 V
Supply current	<45 mA (without external antenna)
External antenna requirements	Supply voltage 3.0 V Consumption current <50 mA