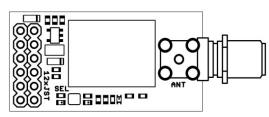


Features: Reference: ELT0051

- Continuous navigation in urban environment, even at signal loss, with speed or wheel-tick information from the vehicle
- On-board low noise 3.3 V voltage regulator and RF filter for noise blocking
- USB, I2C, SPI and UART (Tx, Rx) RAW data out available
- U.FL (I-PEX) active antenna connector
- · Active GNSS antenna support
- 12 pin JST SH connector
- Time pulse LED, Power LED
- u-center GPS evaluation software
- Extensive visualization and evaluation features
- Backup supercapacitor
- Dimensions: 36x18 mm
- Weight: **3.3 gr.**

Hot start





RX/SPI MOSI (O) +5V
TX/SPI MISO (O)O SCL/SPI CLK
EXTINT1 (O)O SDA/SPI CS
USB D(+) (O)O)USB D(-)
EXTINTO (O)O) TIMEPULSE
TIMEPULSE(2)(O)O)GND

GNSS FEATURES	
Receiver type	72-channel u-blox M8 engine GPS/QZSS L1 C/A, GLONASS L10F, Beidou B1I, Galileo E1B/C, SBAS L1 C/A: WAAS, EGNOS, MSAS, GAGAN
GNSS platform	Concurrent GNSS
GNSS bands	L1C/A, L1OF, E1-B/C, B1I
Oscillators	Crystall Oscillator

PERFORMANCE			
Position accuracy	1.5 m CEP	(with SBAS)	
(GPS)	2.5 m CEP	(without SBAS)	
Attitude accuracy (GPS)	3.0 m CEP	(with SBAS)	
Position error during	Rear wheel	ticks	12%
GNSS loss	Gyro + spee	ed pulse	3%
	Gyro + spee	ed pulse + acceleromete	er 2%
Max nav. update rate	30 Hz	•	
Nav update rate (PVT)	2 Hz		
Navigation latency	<10 ms		
Max sensor output rate	100 Hz		
Acquisition	Cold start	Hot start	Aided start
GPS+GLONASS	26 s	1.5 s	3 s
GPS	30 s	1.5 s	3 s
GLONASS	31 s	1.5 s	3 s
Beidou	39 s	1.5 s	7 s
Galileo	57 s	1.5 s	7 s
Velocity accuracy	0.05 m/s		
Heading accuracy	1 deg		
Sensitivity (GPS+GLO):			
Tracking and Navigation	-167 dBm		
Reacquisition	-160 dBm		
Cold start	-148 dBm		

-157 dBm

OTHER FEATURES	
Anti-spoofing	Spoofing detection
Memory	Flash
Operating temperature	0 °C to +50 °C
Supply voltage	4.5 V to 5.5 V
Supply current	<45 mA (without external antenna)
External antenna requirements	Supply voltage 3.0 V Consumption current <50 mA